

Sabre

A Narrative Planner Supporting Intention and Deep Theory of Mind

Stephen G. Ware

Cory Siler



GLAIVE

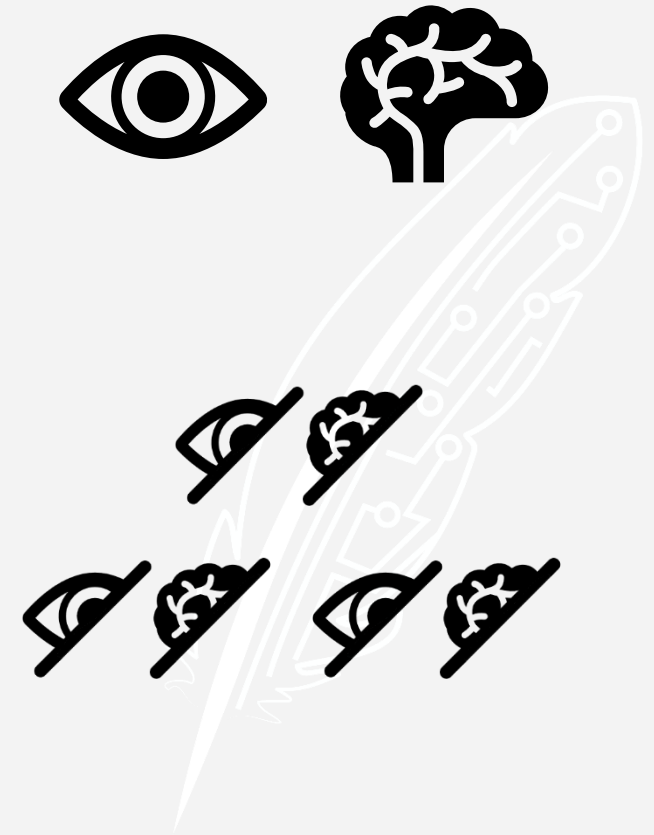
NARRATIVE PLANNER

SABRE

NARRATIVE PLANNER

Narrative Planning

A single decision maker
creates the appearance
of a multi-agent system.

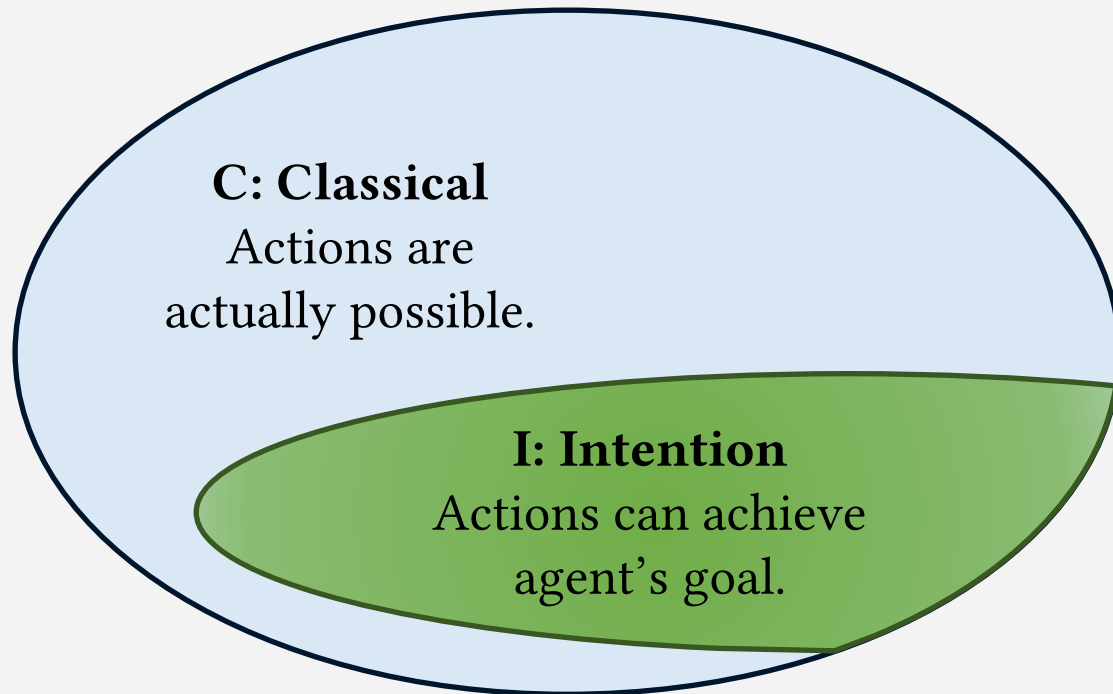


Intentions and Beliefs

C: Classical
Actions are
actually possible.



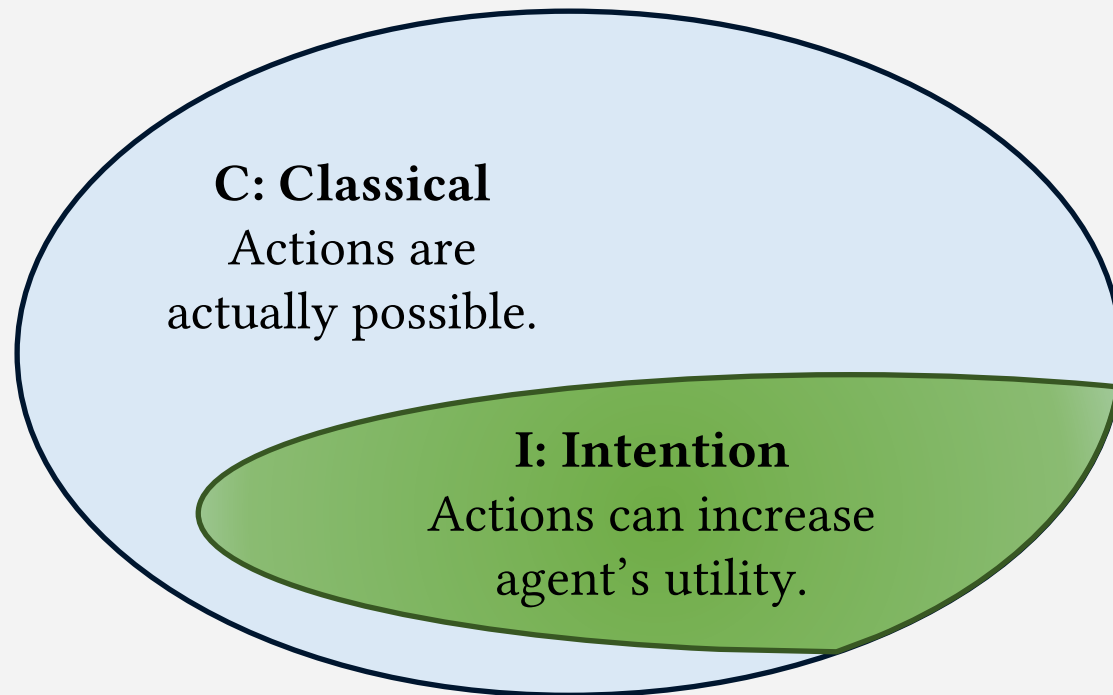
Intentions and Beliefs



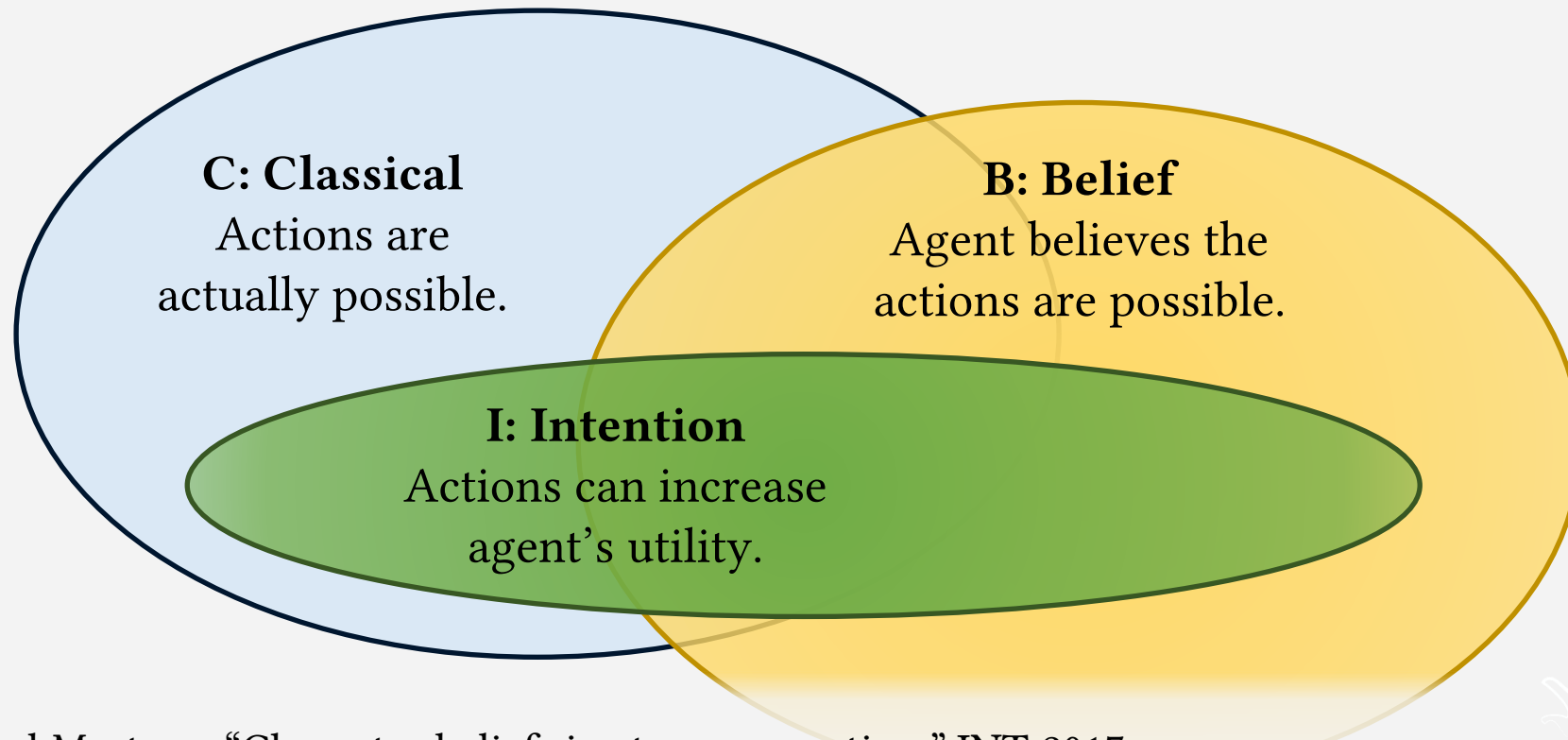
- Riedl and Young, “Narrative planning: balancing plot and character,” in JAIR 2010
- Teutenberg and Porteous, “Efficient intent-based narrative generation...,” in AAMAS 2013
- Ware and Young, “Glaive: a state-space narrative planner...,” in AIIDE 2014



Intentions and Beliefs

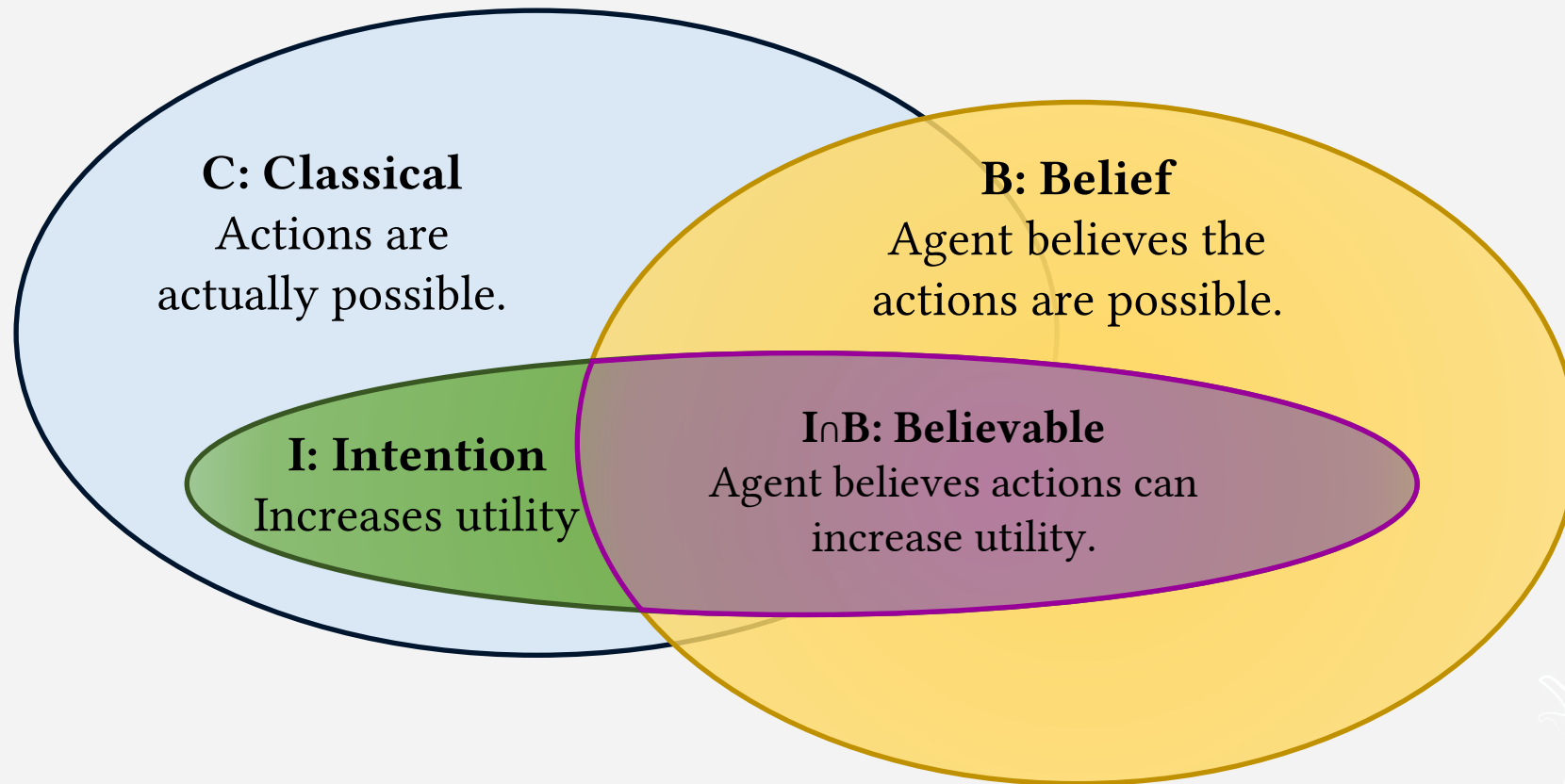


Intentions and Beliefs



- Eger and Martens, “Character beliefs in story generation,” INT 2017
- Thorne and Young, “Generating stories ... by modeling false character beliefs,” in INT 2017
- Shirvani, Ware, and Farrell, “A possible worlds model of belief...,” in AIIDE 2017

Intentions and Beliefs



- Shirvani, Farrell, and Ware, “Combining intentionality and belief...,” in AIIDE 2018

Syntax and Features

Fluents

$at(Tom) =$



Helmert, “The Fast Downward planning system,” in JAIR 2006

Fluents

$at(Tom) = Cottage$



Helmert, “The Fast Downward planning system,” in JAIR 2006

Fluents

$at(Tom) = Cottage$

$path(Cottage, Market) = T$



Fluents

at(Tom) = Cottage

path(Cottage, Market) = T

wealth(Merchant) = 3



Fluents

$at(Tom) = Cottage$

$path(Cottage, Market) = T$

$wealth(Merchant) = 3$

$believes(Tom, wealth(Merchant)) = 2$



Fluents

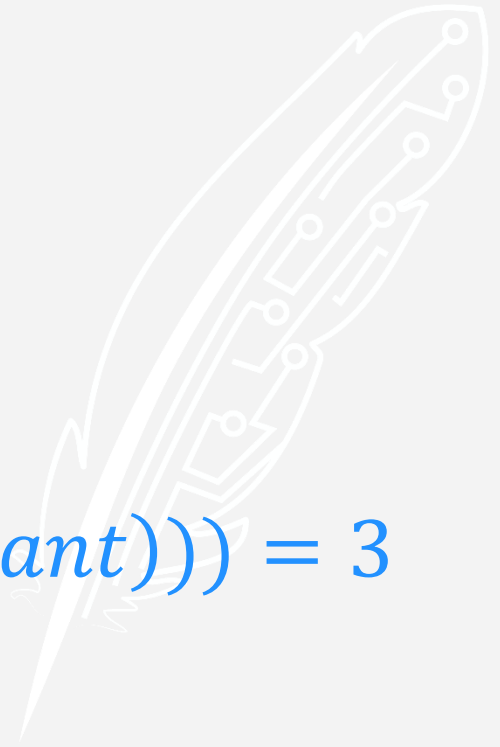
$at(Tom) = Cottage$

$path(Cottage, Market) = T$

$wealth(Merchant) = 3$

$believes(Tom, wealth(Merchant)) = 2$

$believes(Merchant, believes(Tom, wealth(Merchant))) = 3$



Theory of Mind

- Arbitrarily deep
 - what x believes y believes z believes...
- No uncertainty
 - Everyone commits to beliefs, which can be wrong.



Other Syntactical Features

- Negation
- Disjunction
- Conditional Effects
- First Order Quantifiers



Actions

buy(Tom, Potion, Merchant, Market)



Actions

a: buy(Tom, Potion, Merchant, Market)



Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*):



Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market*



Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market*



Actions

a: buy(Tom, Potion, Merchant, Market)

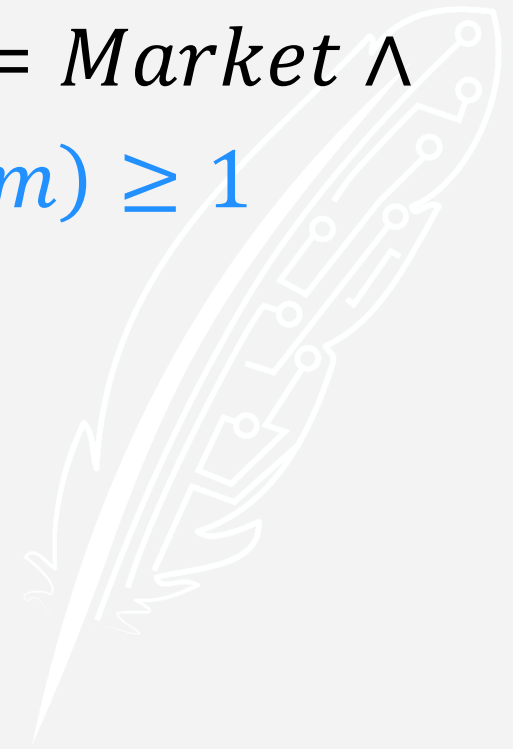
PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant



Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

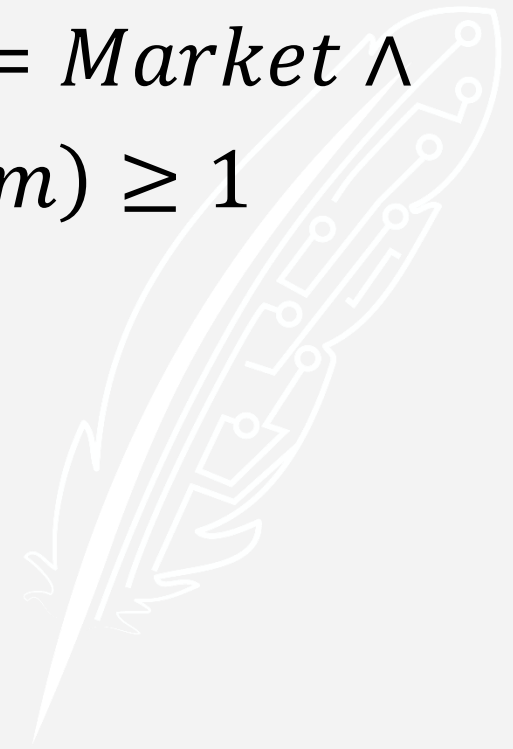


Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*):

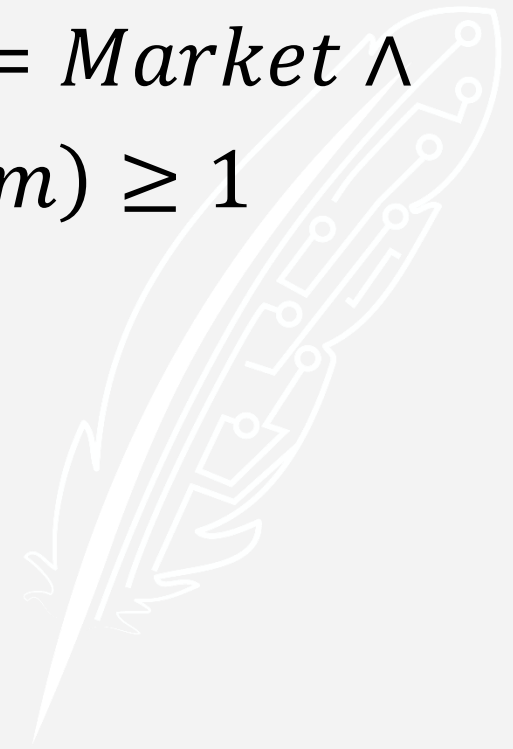


Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom*

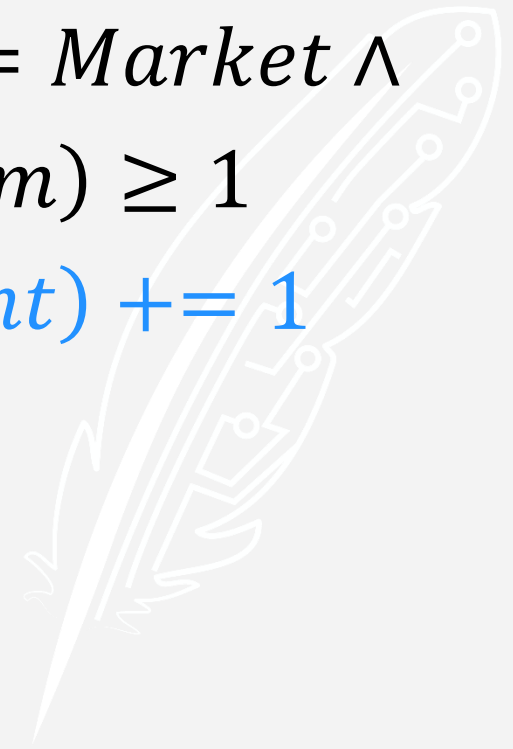


Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1*



Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1* \wedge
wealth(Tom) -= 1

Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1* \wedge
wealth(Tom) -= 1

CON(*a*):

Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1* \wedge
wealth(Tom) -= 1

CON(*a*): {*Tom, Merchant*}

Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1* \wedge
wealth(Tom) -= 1

CON(*a*): {*Tom, Merchant*}

OBS(*a, c*):

Actions

a: buy(Tom, Potion, Merchant, Market)

PRE(*a*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
at(Potion) = Merchant \wedge *wealth(Tom) \geq 1*

EFF(*a*): *at(Potion) = Tom* \wedge *wealth(Merchant) += 1* \wedge
wealth(Tom) -= 1

CON(*a*): {*Tom, Merchant*}

OBS(*a, c*): *at(c) = Market*

Triggers

t: see(Tom, Merchant, Market)

PRE(*t*):

EFF(*t*):



Triggers

t: see(Tom, Merchant, Market)

PRE(*t*): *at(Tom) = Market*

EFF(*t*):



Triggers

t: see(Tom, Merchant, Market)

PRE(*t*): *at(Tom) = Market* \wedge *at(Merchant) = Market*

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Triggers

t: see(Tom, Merchant, Market)

PRE(*t*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
believes(Tom, at(Merchant)) \neq Market

EFF(*t*):



Triggers

t: see(Tom, Merchant, Market)

PRE(*t*): *at(Tom) = Market* \wedge *at(Merchant) = Market* \wedge
believes(Tom, at(Merchant)) \neq *Market*

EFF(*t*): *believes(Tom, at(Merchant)) = Market*



Pre-Processing

- Make action and trigger results explicit
- Detect and remove immutable fluents
- Detect and remove impossible actions and triggers



Results of an Event

After Tom buys the potion from the merchant...

- Tom has the potion.
- Tom knows he has the potion.
- The merchant knows Tom has the potion.
- Tom know that the merchant knows that he has the potion.
- ... and so on.



Example Trigger: Two-Way Paths

t: add_path(y, x)

PRE(*t*) $path(x, y) = \top \wedge path(y, x) = \perp$

EFF(*t*): $path(y, x) = \top$



Example Trigger: Two-Way Paths

t: add_path(Market, Cottage)

PRE(*t*): *path(Cottage, Market) = T* \wedge

path(Market, Cottage) = \perp

EFF(*t*): *path(Market, Cottage) = T*



Example Action: Walk

a: walk(Tom, Market, Cottage)

PRE(*a*): *at(Tom) = Market* \wedge

path(Market, Cottage) = \top

EFF(*a*): *at(Tom) = Cottage*

CON(*a*): {*Tom*}

OBS(*a, c*): *at(c) = Market* \vee *at(c) = Cottage*



Example Action: Walk

a: walk(Tom, Market, Cottage)

PRE(*a*): *at(Tom) = Market* \wedge

path(Market, Cottage) = T

EFF(*a*): *at(Tom) = Cottage*

CON(*a*): {*Tom*}

OBS(*a, c*): *at(c) = Market* \vee *at(c) = Cottage*



Example Action: Walk

a: walk(Tom, Market, Cottage)

PRE(*a*): *at(Tom) = Market*

EFF(*a*): *at(Tom) = Cottage*

CON(*a*): {*Tom*}

OBS(*a, c*): *at(c) = Market* \vee *at(c) = Cottage*



Search

Algorithm 1 The Sabre algorithm

- 1: Let \mathcal{A} be the set of all actions defined in the domain.
 - 2: $\text{SABRE}(c_{author}, s_0, \emptyset, s_0)$
 - 3: **function** $\text{SABRE}(c, r, \pi, s)$
 - 4: **Input:** character c , start state r , plan π , current state s
 - 5: **if** $u(c, s) > u(c, r)$ and π is non-redundant **then**
 - 6: **return** π
 - 7: Choose an action $a \in \mathcal{A}$ such that $s \models \text{PRE}(a)$.
 - 8: **for all** $c' \in \text{CON}(a)$ such that $c' \neq c$ **do**
 - 9: Let state $b = \alpha(a, \beta(c', s))$.
 - 10: **if** b is undefined **then return** failure.
 - 11: **else if** $\text{SABRE}(c', b, \emptyset, b)$ fails **then return** failure.
 - 12: **return** $\text{SABRE}(c, r, \pi \cup a, \alpha(a, s))$
-

So



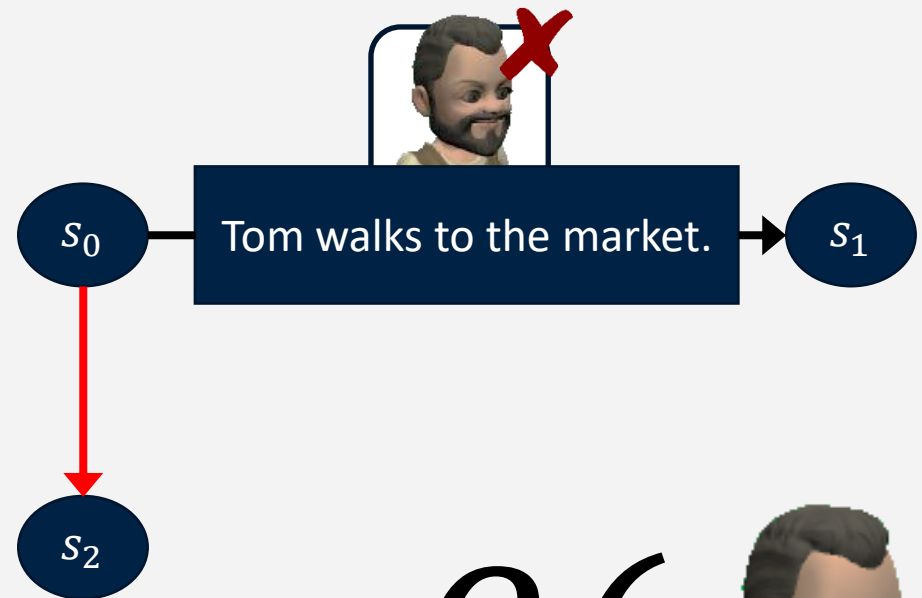
So





$$\alpha(\text{Tom walks to the market.}, s_0) = s_1$$





$$\beta(\text{Tom}, s_0) = s_2$$

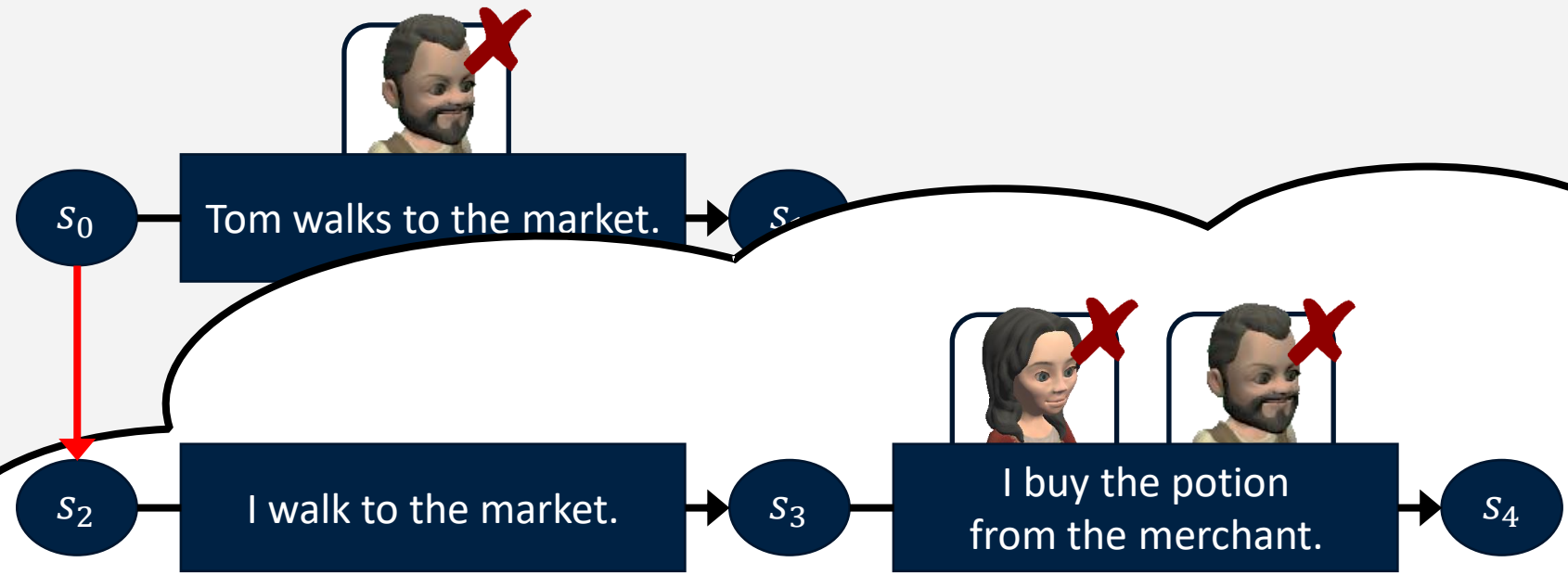


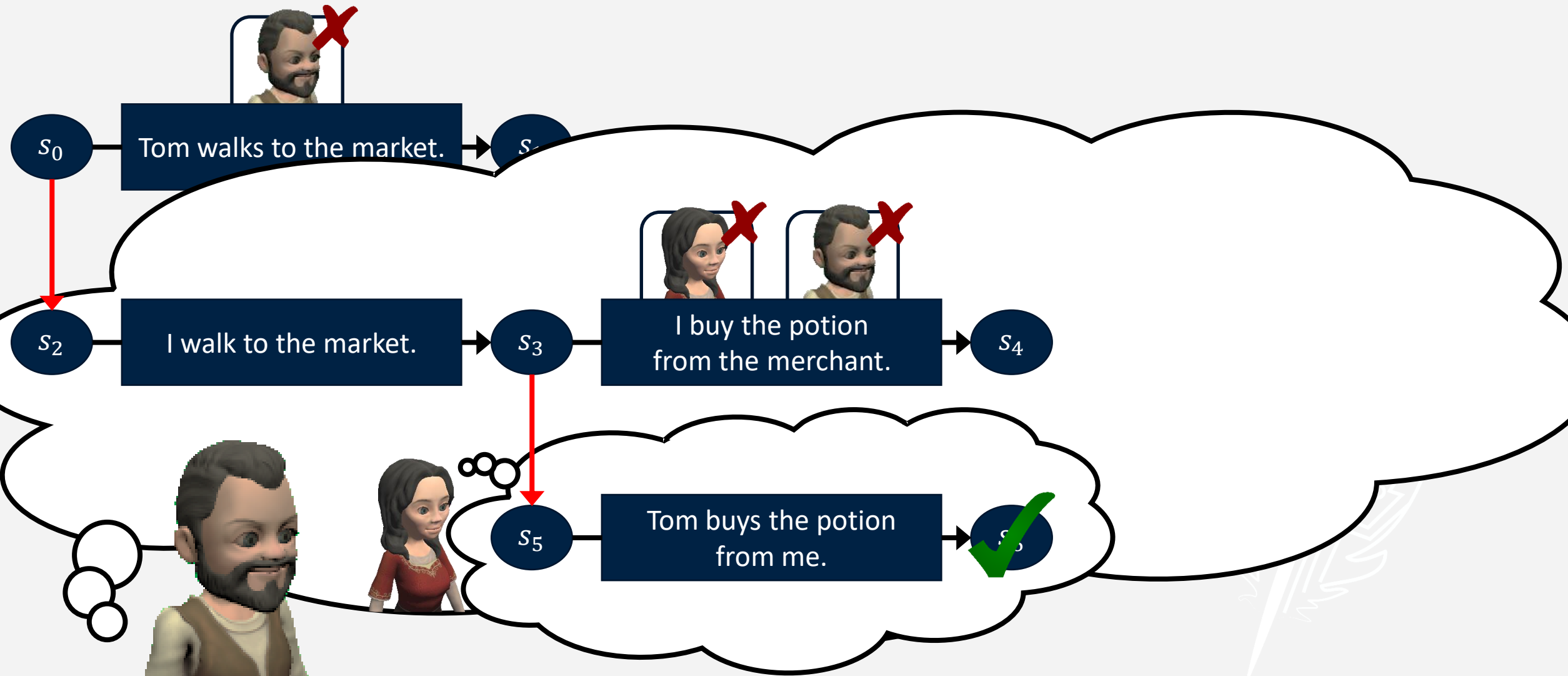


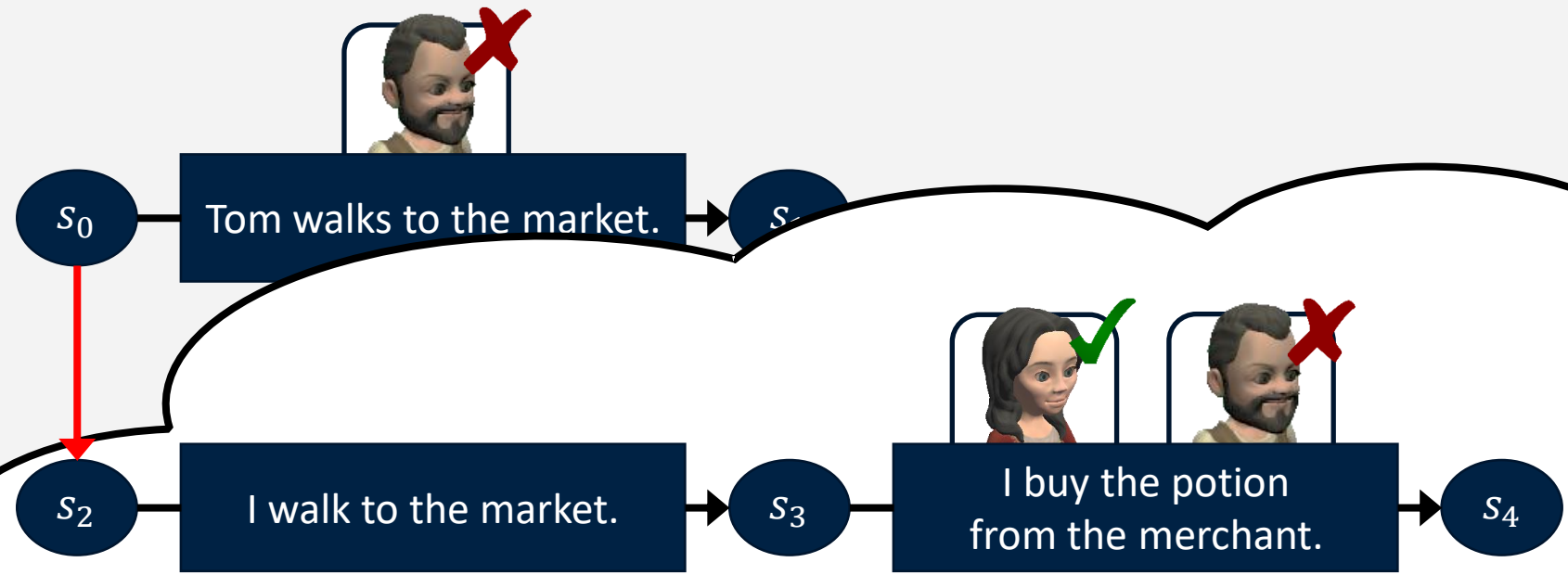
s_0 Tom walks to the market. s_1

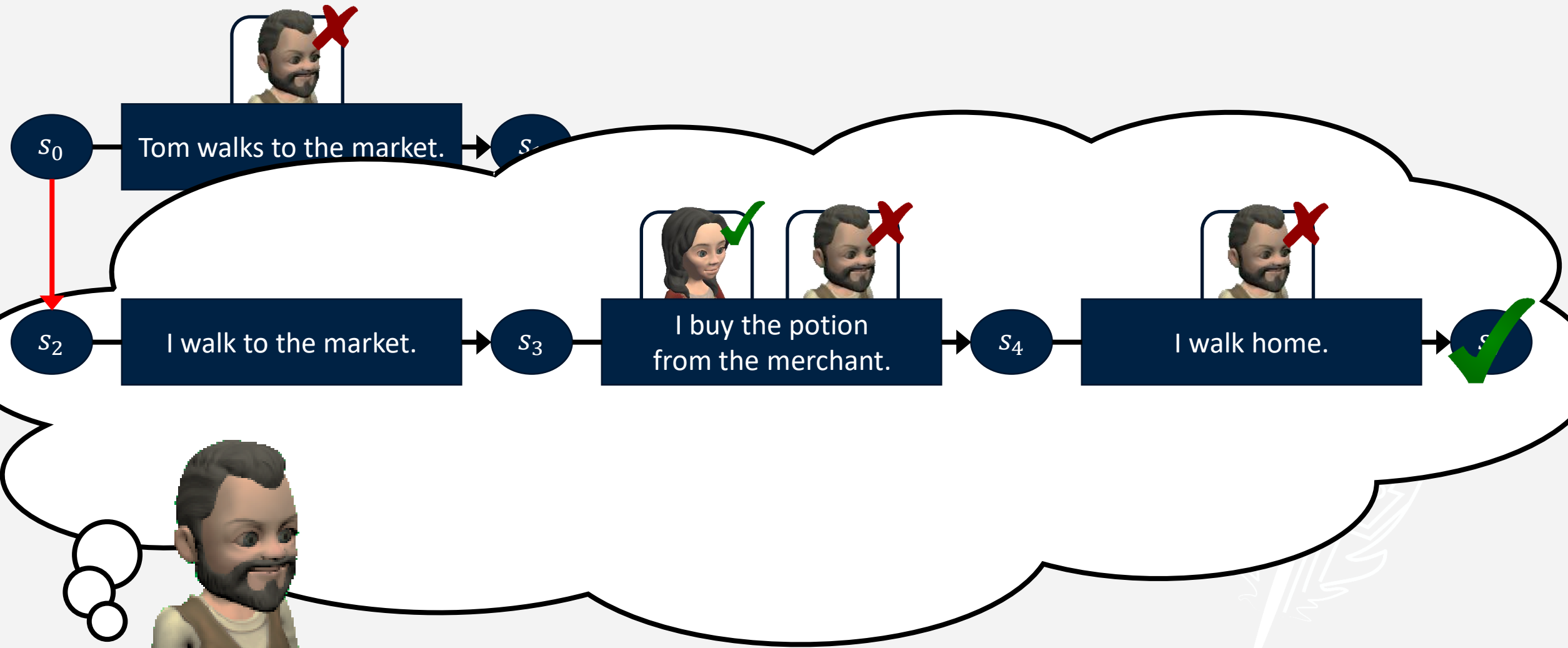
s_2 I walk to the market. s_3

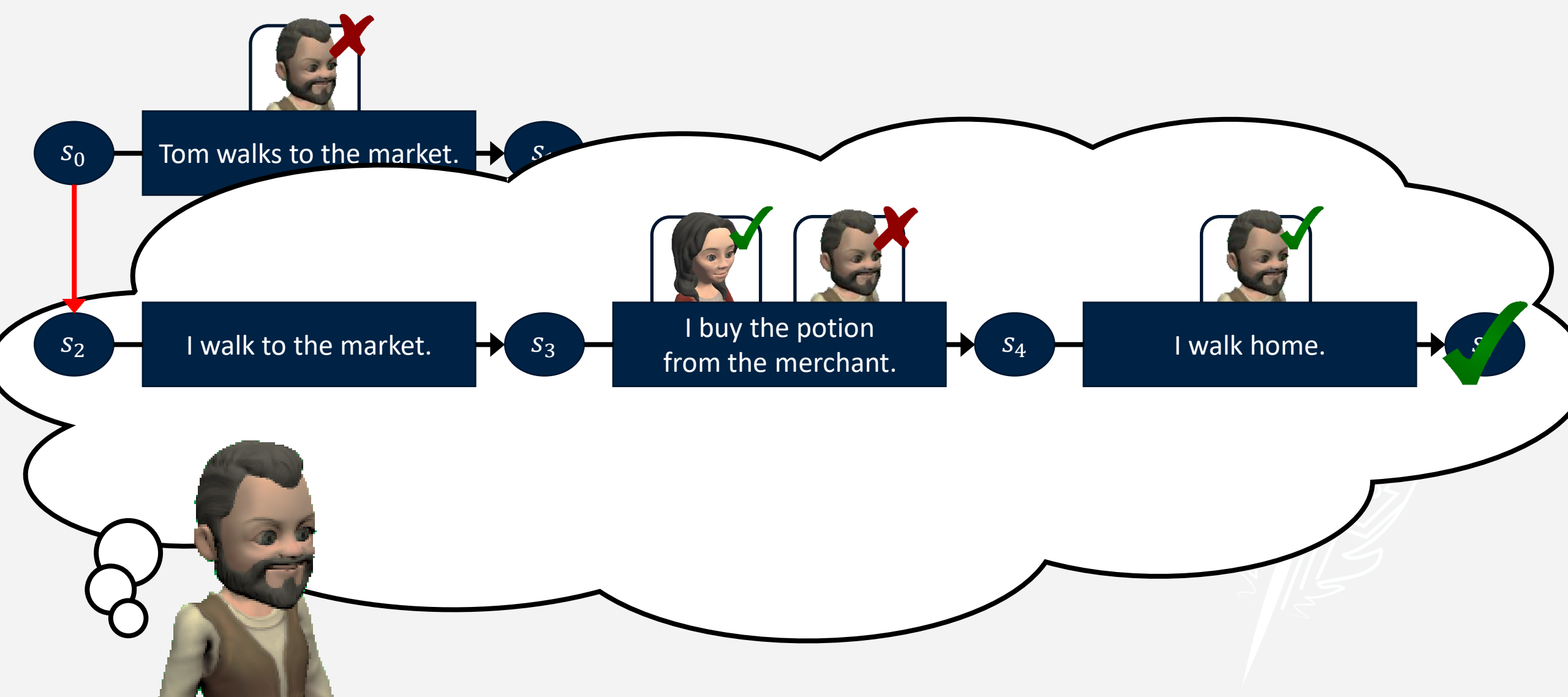


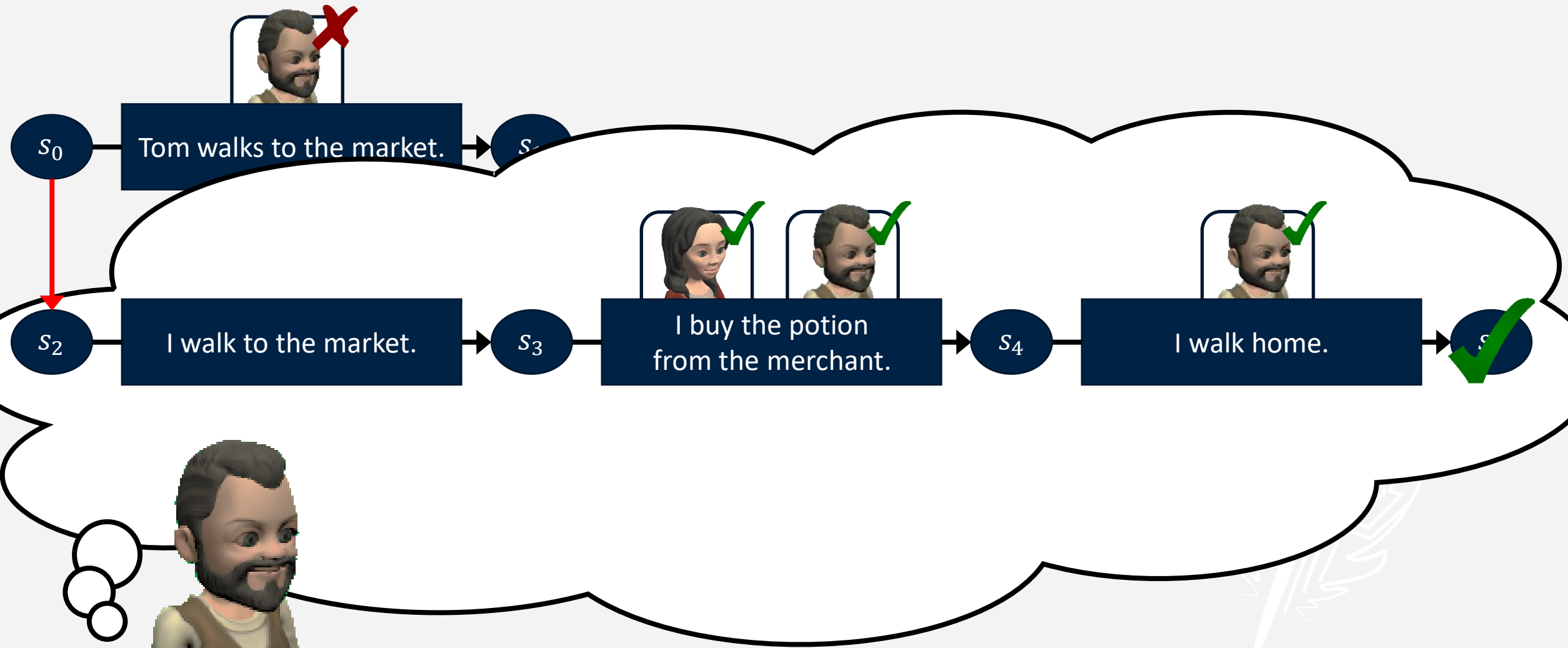


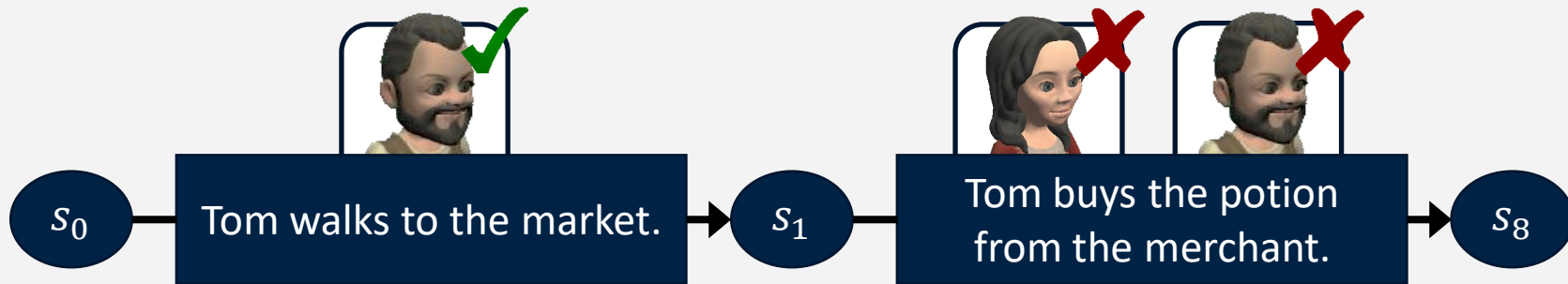


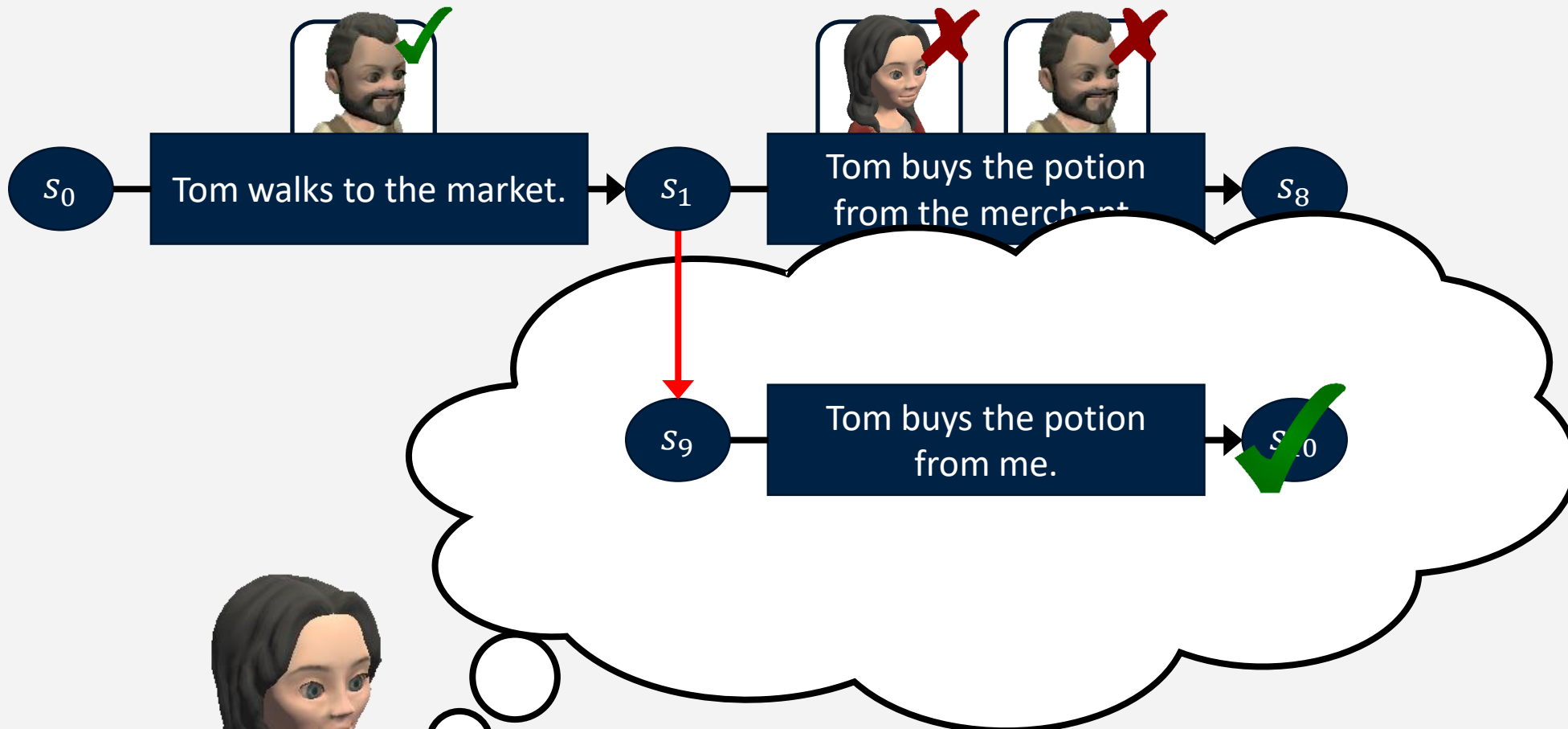


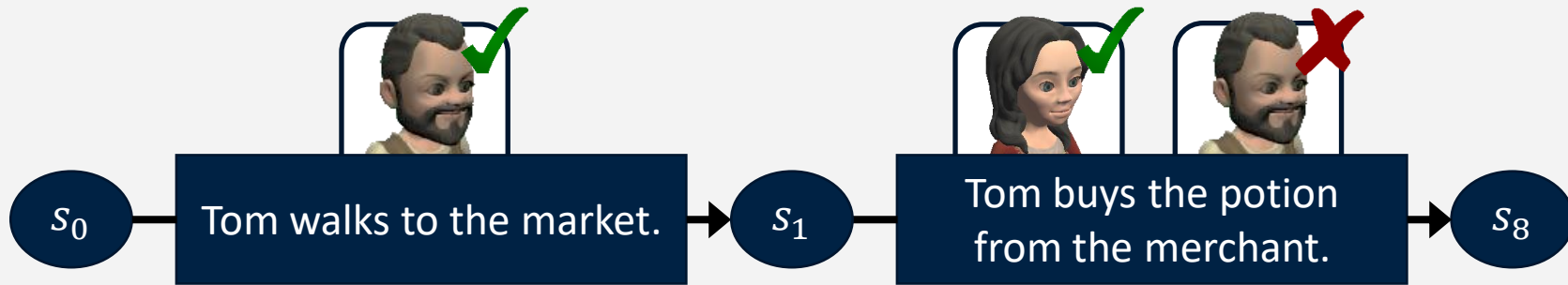


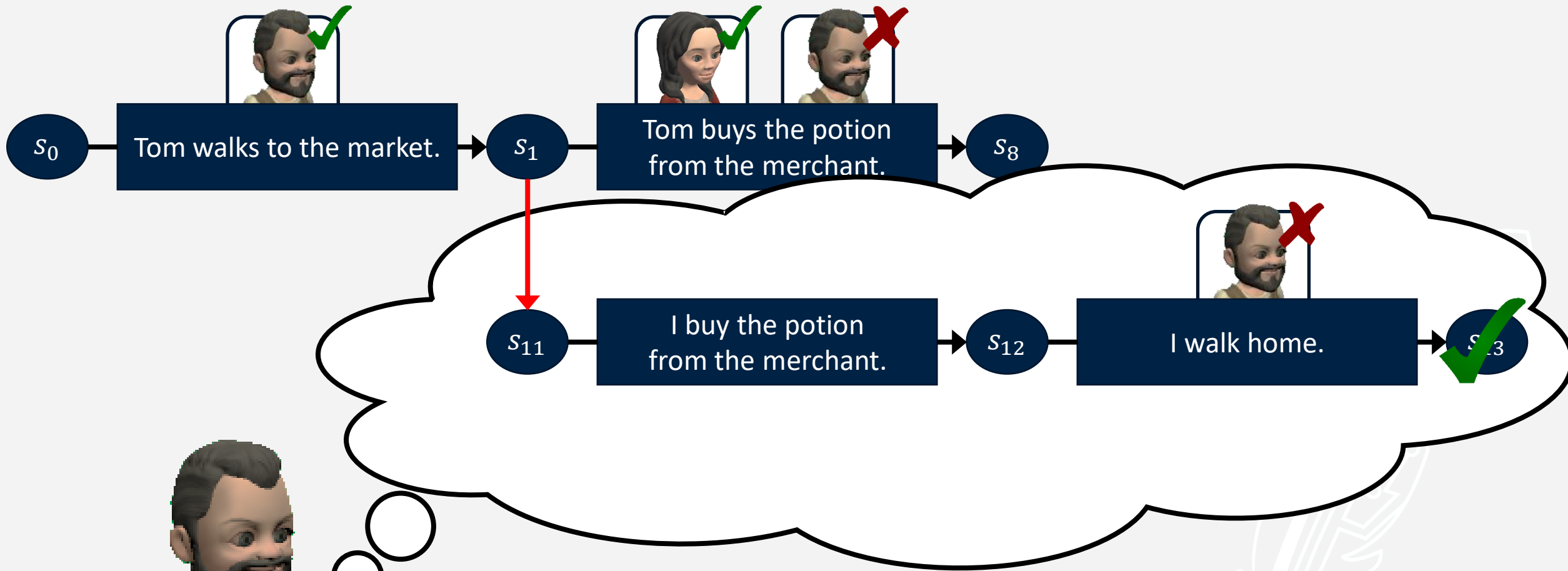


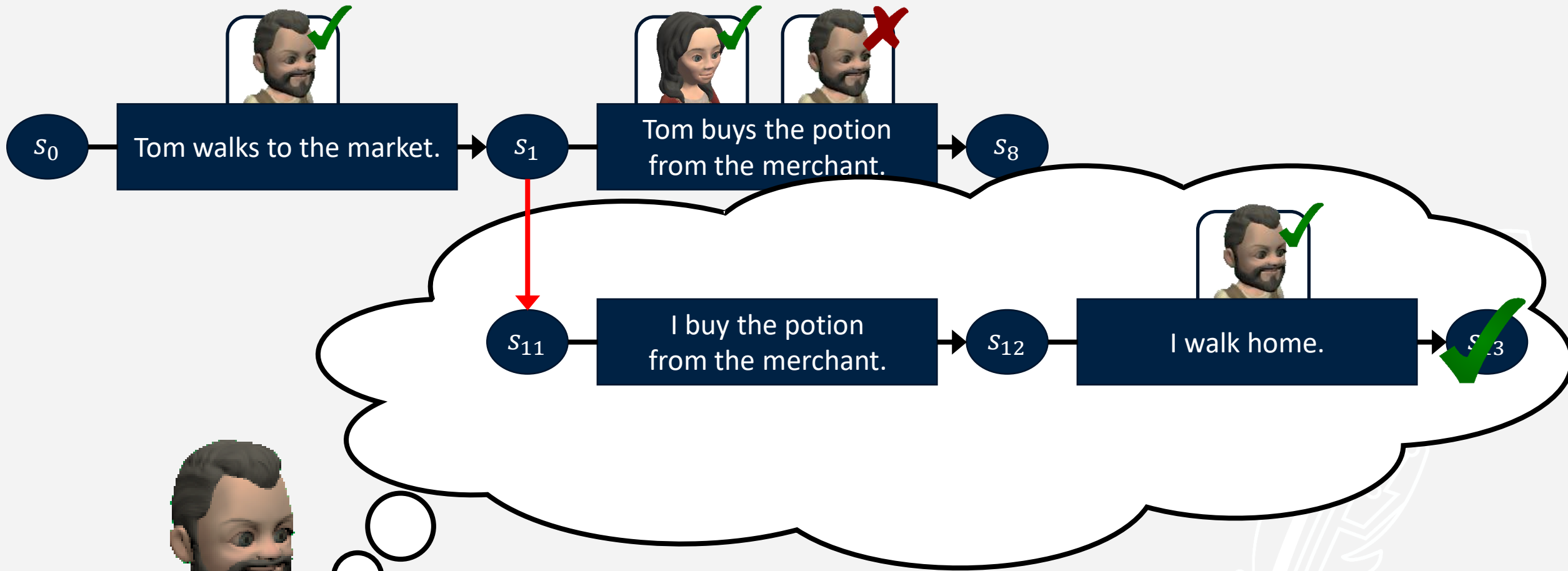


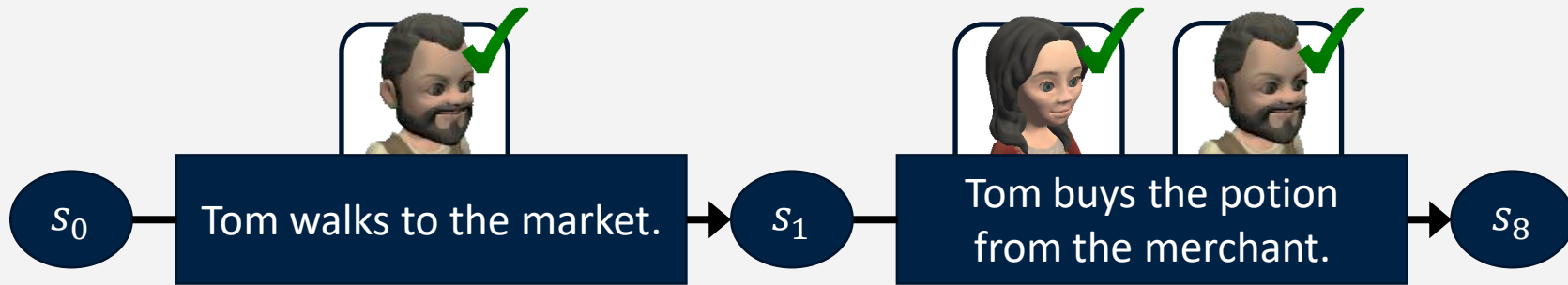


















Evaluation

Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
Sabre	✓	✓	✓	✗



Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
Sabre	✓	✓	✓	✗
Glaive	✓	✓	✗	✗

- Riedl and Young, “Narrative planning: balancing plot and character,” in JAIR 2010
- Ware and Young, “CPOCL: a narrative planner supporting conflict,” in AIIDE 2011
- Teutenberg and Porteous, “Efficient intent-based narrative generation...,” in AAMAS 2013
- Ware and Young, “Glaive: a state-space narrative planner...,” in AIIDE 2014

Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
Sabre	✓	✓	✓	✗
Glaive	✓	✓	✗	✗
HeadSpace	✓	✗	~✓	✗

- Thorne and Young, “Generating stories ... by modeling false character beliefs,” in INT 2017

Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
Sabre	✓	✓	✓	✗
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HeadSpace	✓	✗	~✓	✗
IMPRACTical	✓	✓	~✓	✗

- Teutenberg and Porteous, “Incorporating global and local knowledge...,” in AAMAS 2015

Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
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HeadSpace	✓	✗	~✓	✗
IMPRACTical	✓	✓	~✓	✗
Thespian	✗	✓	✓	✓

- Ryan, Summerville, Mateas, and Wardrip-Fruin, “Toward characters who observe...,” in EXAG 2015
- Si and Marsella, “Encoding Theory of Mind in character design...,” in AHCI 2014

Comparing Sabre to Other Planners

	Centralized	Intentions	Beliefs	Uncertainty
Sabre	✓	✓	✓	✗
Glaive	✓	✓	✗	✗
HeadSpace	✓	✗	~✓	✗
IMPRACTical	✓	✓	~✓	✗
Thespian	✗	✓	✓	✓
Ostari	✓	✓	✓	✓

- Eger and Martens, “Practical specification of belief manipulation in games,” in AIIDE 2017

Test Problems

- *Raiders*
- *Space*

- Ware and Young, “Glaive: a state-space narrative planner...,” in AIIDE 2014



Test Problems

- *Raiders*
 - *Space*
 - *Treasure*
 - *Lovers*
 - *Hubris*
-
- Farrell and Ware, “Narrative planning for belief and intention recognition,” in AIIDE 2020
 - Shirvani, Farrell, and Ware, “Combining intentionality and belief ...,” in AIIDE 2018
 - Christensen, Nelson, and Cardona-Rivera, “Using domain compilation to add belief ...,” in AIIDE 2020



Test Problems

- *Raiders*
- *Space*
- *Treasure*
- *Lovers*
- *Hubris*
- *BearBirdjr*

- Sack, “Micro-TaleSpin, a story generator,” 1992
- Meehan, “TALE-SPIN, an interactive program that writes stories,” in AAAI 1977



Test Problems

- *Raiders*
- *Space*
- *Treasure*
- *Lovers*
- *Hubris*
- *BearBirdJr*
- *Grandma*



- Ware, Garcia, Shirvani, and Farrell, “Multi-agent experience management ...,” in AIIDE 2019

Results

Domain	Nodes Generated	Time
<i>Raiders</i>	17,815	1.4 s
<i>Space</i>	192	6 ms
<i>Treasure</i>	288	1 ms
<i>Lovers</i>	5,198,414	40.3 m
<i>Hubris</i>	831	47 ms
<i>BearBirdJr</i>	34,084,068	14.0 m
<i>Grandma</i>	105,178,466	6.2 h



Conclusion

Limitations

- No true uncertainty
- h^+ heuristic often performs poorly¹



1. Bonet and Geffner, “Planning as heuristic search,” in AI, 2001

Future Work

- More search methods

Algorithm 1 The Sabre algorithm

```
1: Let  $\mathcal{A}$  be the set of all actions defined in the domain.
2:  $\text{SABRE}(c_{author}, s_0, \emptyset, s_0)$ 
3: function  $\text{SABRE}(c, r, \pi, s)$ 
4:   Input: character  $c$ , start state  $r$ , plan  $\pi$ , current state  $s$ 
5:   if  $u(c, s) > u(c, r)$  and  $\pi$  is non-redundant then
6:     return  $\pi$ 
7:   Choose an action  $a \in \mathcal{A}$  such that  $s \models \text{PRE}(a)$ 
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11:    else if  $\text{SABRE}(c', b, \emptyset, b)$  fails then return failure.
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12:  return SABRE( $c, r, \pi \cup a, \alpha(a, s)$ )
```

Algorithm 2 The Sabre algorithm

```
1: Let  $\mathcal{A}$  be the set of all actions defined in the domain.
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3: function SABRE( $c, r, \pi, s$ )
4:   Input: character  $c$ , start state  $r$ , plan  $\pi$ , current state  $s$ 
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12:    else if SABRE( $c', b, \emptyset, b$ ) fails then return failure.
13:  return  $\pi$ 
```

Future Work

- More search methods
- Better heuristics
- Agent emotions and personalities¹



1. Shirvani and Ware, “A formalization of emotional planning for strong-story systems,” in AIIDE 2020

SABRE

NARRATIVE PLANNER



<http://cs.uky.edu/~sgware/projects/sabre>

Background Music: <https://www.bensound.com>